

**ERRATA for**  
***FE Mechanical Practice Exam***  
ISBN: 978-1-932613-85-8  
Copyright 2017  
Errata posted 8/2/2018

**Revisions are shown in red.**

**Question 35, p. 30:**

The figure shows a four-bar linkage. If Link 3 rotates in the counterclockwise direction, the angle **of the velocity vector of** Point P, measured in the global X-Y coordinate frame, is most nearly:

*Previously posted errata continued on next page*

**ERRATA for**  
***FE Mechanical Practice Exam***  
ISBN: 978-1-932613-85-8  
Copyright 2017  
Errata posted 8/22/2017

**Revisions are shown in red.**

**Question 78, p. 59:**

The options should read as follows:

- A. 348
- B. **148**
- C. 1.10
- D. 0.90

**Solution 78, p. 117:**

The solution should read as follows:

$$\begin{aligned} \text{Re} &= \frac{v(2r_i)P}{\mu} \\ &= \frac{6 \text{ m/s}(2 \cdot 0.050 \text{ m})(10.844 \text{ kg/m}^3)}{2.0417 \times 10^{-5} \text{ kg/m}\cdot\text{s}} \\ &= \mathbf{318,676} \\ h_i &= \mathbf{0.023} \frac{k_f}{2r_i} \text{Re}^{0.8} \text{Pr}^{1/3} \left( \frac{\mu_b}{\mu_s} \right)^{0.14} \\ &= \mathbf{0.023} \left( \frac{0.0245 \text{ kJ/m}\cdot\text{K}}{2 \cdot 0.050 \text{ m}} \right) (\mathbf{318,676})^{0.8} (1.12)^{1/3} (1)^{0.14} \\ &= \mathbf{147.9} \text{ W/m}^2\cdot\text{K} \end{aligned}$$

**THE CORRECT ANSWER IS: B**